Amendments to the Specification

Please replace the paragraph beginning at page 2, line 12, with the following rewritten paragraph:

--The object of the present invention is to be able to limit the movement of the lever, alternatively to wholly lock the control lever in certain positions. The said object is achieved by means of a controller and a method for controlling [this, the characteristics of which can be seen from the Independent Patent Claims 1 and 12, and their subordinate claims] the controller, as described herein.--

Please replace the paragraph beginning at page 3, line 15, with the following rewritten paragraph:

--In all three embodiments above, it is, of course, possible to choose freely which clamp is to be locked and [.] to lock a further clamp in order to lock the control lever in a fixed position.--

Please replace the paragraph beginning at page 3, line 24, with the following rewritten paragraph;

--The detention arm, at its other end, is provided with an [activable] activatable member when activated, moves the detention arm into the detention position locking the clamp. An activatable member of this kind may comprise an electromagnet, a pneumatically or hydraulically operated piston-cylinder unit, a mechanically operated cam, or the like.--

Please replace the paragraph beginning at page 3, line 28 and bridging to page 4, line3, with the following rewritten paragraph:

--In certain cases it can be desirable for the detention devices only to be [activable] activatable when the control lever is placed in certain predefined positions. In order to achieve this, the console can be provided with some form of position transmitter,

preferably a contactless transmitter, coupled to a control unit, for detecting the position of the control lever relative to the console.--

Please replace the paragraph beginning at page 7, line 5, with the following rewritten paragraph:

--The one end of the respective clamp 42, 43 is provided with a holder 45, 46, which bears a magnetic element in the form of a plurality of magnetic and negative poles 47 placed on each side of a Hall element 48, which, in turn, is mounted on a fixed-mounted holder 49. Each magnetic element is divided into a number of sectors, for example circular segments, whereby a displacement of the respective pair of magnets induces a current proportional to the position of the clamp in the Hall element [By] by using a pair of Hall elements cooperating with magnetic elements fixed to two cross-laid clamps 42, 43 controlled by the guide pin 41, a position sensor is obtained whose output signal indicates the position of the control lever 1. The respective Hall element 47, 48 is coupled to a control unit 50, which is programmed to execute certain predefined measures depending on the signals from the sensor.--